



Application Note

AN_186

Vinculum-II SPI to USB Memory Bridge

Version 1.0

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This application note forms part of a series of application notes detailing the new simplified ROM images for VNC2. It will detail the implementation and use of a VNC2 ROM file for bridging a SPI slave interface to hosting a USB memory device.

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1 Introduction

FTDI have introduced a new suite of simplified “bridging” ROM files to allow for fast interconnect between differing interfaces. These ROM images (and sample code) are targeted at those users who would like to implement VNC2 into a design without creating their own firmware.

As well as providing the source code for users wishing to tweak setup parameters the default project will be supplied as a precompiled ROM file ready for installation into the VNC2.

This application note forms part of a series of application notes detailing the new simplified ROM images for VNC2. This document will detail the implementation and use of a VNC2 ROM file for bridging a SPI interface to hosting a Bulk Only Mass storage (BOMS) class device on a USB port (USB memory). This particular project may be used in 32, 48 or 64 pin packages.

For users not intending to edit the code in any way the precompiled code may be loaded over the UART interface with [FT_PROG](#) as an alternative to using the IDE. Links for the project file SPI2DSC.vproj and the precompiled ROM file SPI2DSC.rom file may be found at the end of the document in Appendix A.

1.1 VNC2 Devices

VNC2 is the second of FTDI’s Vinculum family of embedded dual USB host controller devices. The VNC2 device provides USB Host interfacing capability for a variety of different USB device classes including support for BOMS (bulk only mass storage), Printer and HID (human interface devices). For mass storage devices such as USB Flash drives, VNC2 transparently handles the FAT file structure.

Communication with non USB devices, such as a low cost microcontroller, is accomplished via either UART, SPI or parallel FIFO interfaces. VNC2 provides a new, cost effective solution for providing USB Host capability into products that previously did not have the hardware resources available.

VNC2 allows customers to develop their own firmware using the Vinculum II software development tool suite. These development tools provide compiler, assembler, linker and debugger tools complete within an integrated development environment (IDE).

The Vinculum-II VNC2 family of devices are available in Pb-free (RoHS compliant) 32-lead LQFP, 32-lead QFN, 48-lead LQFP, 48-lead QFN, 64-Lead LQFP and 64-lead QFN packages For more information on the ICs refer to <http://www.ftdichip.com/Products/ICs/VNC2.htm>.

2 Using the Sample Code

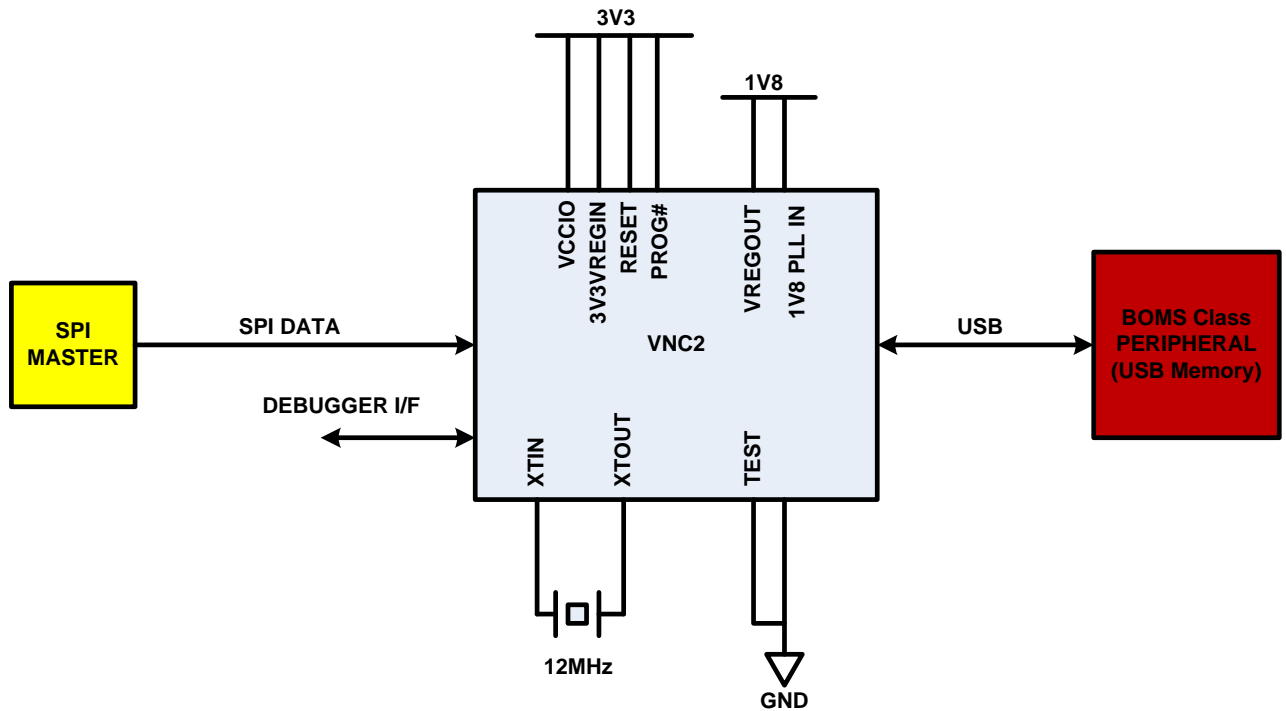


Figure 2.1 Connecting the Demo

When the VNC2 is programmed, the user simply passes data from the SPI master to the VNC2. This data will be appended to a file named "TEST.TXT".

The default configuration of the SPI slave port on the VNC2 is:

- Clock phase, CPHA = 0
- Clock polarity, CPOL = 0
- Data order is MSB first
- Address = 0
- VNC2 SPI mode = unmanaged

There are no additional commands required; it is a simple data bridge.

2.1 LEDs

Although GPIO lines have been reserved for LED driving the pins were not coded to signal anything.

3 Default Pin-Out

Signal	32-pin pkg	48-pin pkg	64-pin pkg	Description
GND	1, 16, 19, 27	1, 24, 27, 39	1, 30, 35, 53	Device ground supply pins
3V3 VREGIN	2	2	2	+3.3VDC supply to the regulator
1V8 VCC PLL IN	3	3	3	+1.8VDC supply to internal clock multiplier Requires 100nF decoupling capacitor close to pin
GND PLL	6	6	6	Device analog ground supply for internal clock multiplier
VREG OUT	7	7*	7	+1.8VDC output from regulator to device core *Not used on 48-pin LQFP package
VCCIO	13, 22, 28	17, 30, 40	21, 38, 54	+3.3VDC supply to I/O interface pins (IOBUS) VCCIO must be connected for proper operation
XTIN	4	4	4	Input to 12MHz Oscillator Connect 12MHz crystal across pins 4 and 5 with proper loading capacitance
XTOUT	5	5	5	Output from 12MHz Oscillator Connect 12MHz crystal across pins 4 and 5 with proper loading capacitance
TEST	8	8	8	Test – Must be connected to GND for normal operation
RESET#	10	9	9	Can be used by an external device to reset VNC2
PROG#	9	10	10	Asserting PROG# enables program mode
DEBUGGER I/F	11	11	11	I/O for programming and in-circuit debugging
USB DP1	17	25	33	USB Port 1 Data Plus
USB DM1	18	26	34	USB Port 1 Data Minus
SPI_S0_CLK	29	15	61	SPI Slave Clock input
SPI_S0_MOSI	30	16	62	SPI MOSI input



Signal	32-pin pkg	48-pin pkg	64-pin pkg	Description
SPI_S0_MISO	31	18	63	SPI MISO output
SPI_S0_SS#	32	19	64	SPI Slave select input

Table 3.1 VNC2 Pin-Out

4 Building and Loading the Firmware in the VNC2

Everything can be controlled by the IDE. To access the application simply use the Project -> Open tab to browse to the SPI2DSC.vproj file for your project.

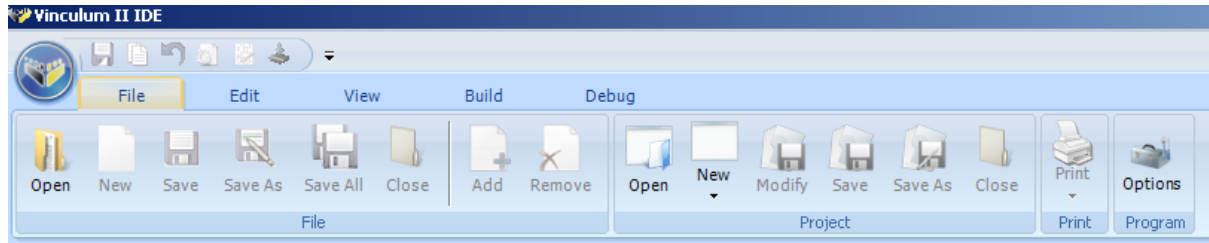


Figure 4.1 Vinculum-II Project Open Button

4.1 Build

This step is only necessary if you are not using the precompiled version of the ROM. Otherwise proceed to loading the ROM file.

To build the application you simply press the Build button on the IDE ribbon bar under the build tab.

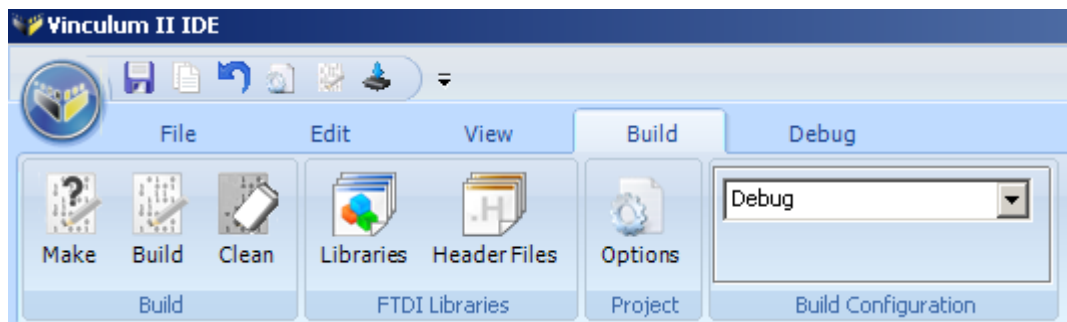


Figure 4.2 Vinculum-II IDE Build Button

4.2 Load

Loading the code is equally simple. Just click on the "Flash" button on the ribbon bar under the debug tab. The Flash button will automatically pick up the Rom file in your project but for reference the filename is SPI2DSC.ROM.

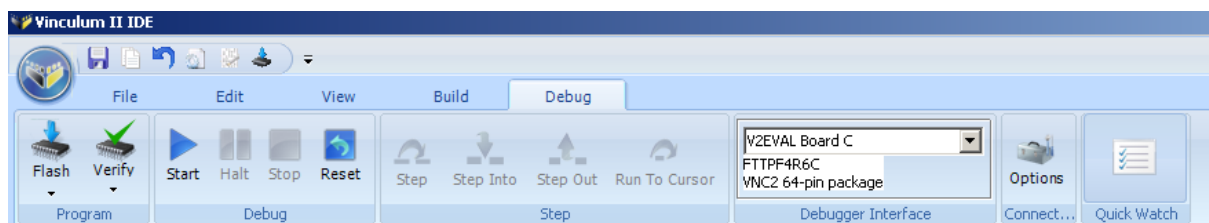


Figure 4.3 Vinculum-II IDE Flash Button

Note the Debugger Interface is listed as V2EVAL Board C. It is important that this box shows a device is connected before attempting to flash a device.

4.3 Loading with FT_Prog

If the precompiled ROM file meets all the requirements of the end design then the IDE and source code are not required. The precompiled FT232Uart.ROM file may be loaded into the VNC2 with FT_PROG over the UART interface.

FT_Prog is used to program the VNC2 with a ROM file. FT_Prog is available from the FTDI website utilities page (version 1.12 or later supports VNC2).

- Select the flash ROM tab at the top of the window.
- Select VNC2 from the pull down tab.
- Select D2xx or VCP interface (either will work).
- Select the location where the ROM file resides.
- Press the program button.
- Perform a hard reset (power cycle) prior to running the firmware.

Figure 4.4 is an example of programming the VNC2 Evaluation board revision 2 with the V2DAP firmware.

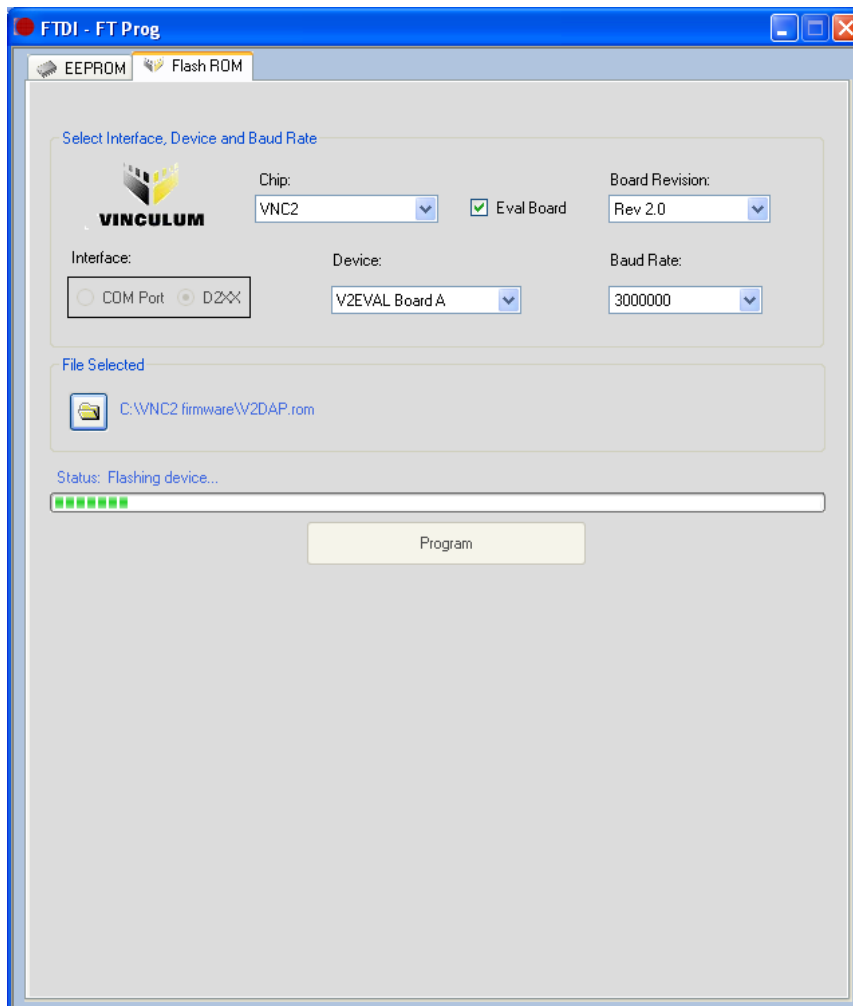


Figure 4.4 FT_Prog Programming Utility

For more information on loading ROM files onto a VNC2 device refer to:

http://www.ftdichip.com/Support/Documents/AppNotes/AN_159%20Vinculum-II%20Firmware%20Flash%20Programming.pdf

5 Source Code for the VNC2 Application

This section is aimed at those wanting to learn about coding VNC2 devices or modify the existing project.

All VNC2 application firmware follows a similar format and most of the code can be “written” using the IDE application wizard.

The basic steps are:

1. Initialise device drivers
2. Define pin-outs
3. Open ports to be used
4. Configure ports to be used
5. Read/write data
6. Close ports

The VNC2 source code for this project can be viewed in appendix A and is available to [download with the toolchain](#).

5.1 SPI2DSC.C

SPI2DSC.c is the main firmware file. This file is split into multiple functions.

```
void main();
void iomux_setup(void);
unsigned char usbhost_connect_state(VOS_HANDLE hUSB)
VOS_HANDLE fat_attach(VOS_HANDLE hMSI, unsigned char devFAT)
void fat_detach();
VOS_HANDLE boms_attach(VOS_HANDLE hUSB, unsigned char devBOMS)
void boms_detach();
void open_drivers(void);
void monError(void);
void setup();
void SPISlave(void)
void BOMS(void)
```

5.1.1 main()

Main is where the application starts. It defines the VNC2 core clock speed, loads the drivers to be used and creates the threads to be used in the application. At the very end of main is the call

```
vos_start_scheduler();
```

After this call there can be no further configuration of the device.

5.1.2 iomux_setup()

Iomux_setup actually refers to the other file in the project, SPI2DSC_iomux.c and is used to define the VNC2 pin-out. Most functions can be programmed to appear on different pins. The notable exceptions are power, GND and the USB ports.

5.1.3 USB_Host_Connect_state

USB_Host_Connect_State is a function to check if anything is connected to the USB host.

5.1.4 fat_attach/ Fat_detach

This section will attach the FAT driver to the BOMS class driver. This is the last layer of the driver construction to connect the USB port to a FAT table in a memory device. Fat_detach disconnects the link.

5.1.5 Boms_attach/ boms_detach

This section will attach the BOMS class driver to the USB host port 1 driver. boms_detach disconnects the link.

5.1.6 Open drivers

The open drivers function call will provide a handle to each hardware block used in the project and this handle can be used by subsequent commands to control the hardware.

5.1.7 monError

This function will light an LED if an error is detected.

5.1.8 Setup

Setup() will ensure the driver handles are opened, the USB driver is connected to the BOMs driver, which is then connected to the FAT driver. It will also configure the SPI slave 0 port.

5.1.9 SPI Slave

This section will allow the VNC2 to read data sent to it over SPI.

5.1.10 BOMS

This section will transfer the data read on the SPI interface to a file named "TEST.txt" on the memory device connected to the USB port of the VNC2.

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Appendix A – References

Document References

Application and Technical Notes available at

<http://www.ftdichip.com/Support/Documents/AppNotes.htm>

[VNC2 Datasheet](#)

[V2-EVAL datasheet](#)

[Vinculum II Toolchain](#)

[AN_139 IO Mux explained](#)

[AN_151 Vinculum II User Guide](#)

[AN_159 Vinculum II Firmware Flash Programming.pdf](#)

Project source code download

<http://www.ftdichip.com/Firmware/Precompiled/SPI2DSC.zip>

Project precompiled ROM file download

<http://www.ftdichip.com/Firmware/Precompiled/SPI2DSC.ROM>

Acronyms and Abbreviations

Terms	Description
SPI	Serial Peripheral Interface
USB	Universal Serial Bus
USB-IF	USB Implementers Forum

Appendix B – List of Tables & Figures

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Appendix C – Revision History

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1.0	Initial Release	2011-11-14